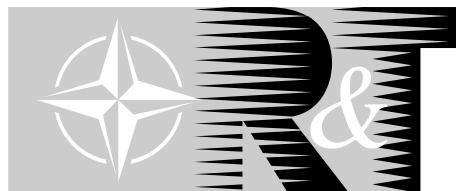


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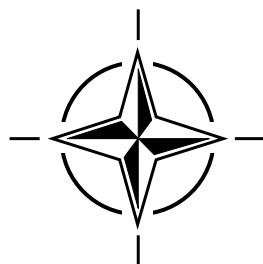
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Development and Operation of UAVs for Military and Civil Applications

(Développement et utilisation des avions sans pilote (UAV)
pour des applications civiles et militaires)

This report is a compilation of the edited proceedings of the “Development and Operation of UAVs for Military and Civil Applications” course held at the von Kármán Institute for Fluid Dynamics (VKI) in Rhode-Saint-Genèse, Belgium, 13-17 September 1999.



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- SET Sensors and Electronics Technology
- IST Information Systems Technology
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Development and Operation of UAVs for Military and Civil Applications

(RTO EN-9)

Executive Summary

This international Special Course brought together 60 engineers and scientists (47 observers and 13 lecturers) from 14 different countries. It was a full five-day course organized from 13th to 17th September 1999.

The first lecture, “UAVs: Overview of the Current Situation and Potential for the Future”, emphasized UAV classification with respect to the mission, vehicle performance, (range, altitude, endurance), the type of payload and the launch and recovery requirements. Problems related to “Airspace Policy and Air Traffic Management” were the subject of the second lecture. These are challenges for which effective solutions are urgently required in the next few years, especially in Europe where the airspace is already very crowded. The first day ended with a lecture on C3, highlighting the issues arising when the crew are removed from the aircraft.

The second day started with a lecture on “Tools for Optimization and Validation of System Architecture and Software”, addressing the need for optimization and the techniques already available today. The lecture on “Design and Airworthiness Requirements for Unmanned Air Vehicle Systems” examined the safety implications and factors to be considered for the procurement of a UAV and identified the design requirements to be used as a guide to produce an air vehicle specification. Aspects of vehicle and payload control were dealt with during the lecture on “UAV Datalinks: Tasks, Types, Techniques and Examples”.

On Wednesday a lecture was given on “The Developmental and Operational Challenges of UAV and UCAV Airbreathing Propulsion”. Benefits, advantages and disadvantages of various types of UAV propulsion technologies were reviewed. Case histories on Pioneer, Predator and Global Hawk were presented. The afternoon was dedicated to micro aerial vehicles. A lecture entitled “Microflyers and Aerial Robots: Missions and Design Criteria” provided an overview of the issues surrounding the design and choice of appropriate missions for this class of unmanned flying vehicles.

“Aerodynamic Measurements at Low Reynolds Numbers for Fixed Wing Micro Air Vehicles” was the subject of a half day lecture given on Thursday. The results of a study of the methods that can be used to obtain reliable force and moment data on thin wings in wind and water tunnels were presented as well as balance characteristics and validation. During the lecture on “Tactical Payloads for UAVs” various imaging and non-imaging sensors were described.

On Friday the main subject of the lecture on “Various sensors aboard UAVs” was Synthetic Aperture Radar (SAR). The working principles, challenges and future developments of this complex imaging sensor were translated into understandable words for observers not familiar with the subject. The lecture on “Use Case Analysis and the Formulation of Functional Requirements for Complex Systems: A Case Study for UAVs” gave an example on how modern mathematical tools can be applied for the elaboration of a Request for Proposal (RFP). Finally, the last lecture entitled “The B-Hunter UAV System” illustrated some modifications and upgrades of the Hunter UAV to fulfill the requirements of the RFP issued by the Belgian Army.

Développement et utilisation des avions sans pilote (UAV) pour des applications civiles et militaires

(RTO EN-9)

Synthèse

Ce cours spécial international a rassemblé 60 ingénieurs et scientifiques (47 observateurs et 13 conférenciers) ressortissants de 14 pays différents pour une période de cinq jours, du 13 au 17 septembre 1999.

Le premier cours, «Les UAV, tour d'horizon de la situation actuelle et perspectives d'avenir» a mis l'accent sur la classification des UAV par rapport à la mission, aux performances (portée, altitude, endurance), au type de charge utile et aux besoins en matière de lancement et de récupération. Les problèmes relatifs à «La politique de gestion de l'espace aérien et la gestion du trafic aérien» ont fait l'objet du deuxième cours. Il s'agissait des défis pour lesquels des solutions efficaces doivent être rapidement trouvées au cours des prochaines années, surtout en Europe où l'espace aérien est déjà très encombré. Le premier jour s'est achevé par un cours sur le C3 qui a mis en relief les problèmes qui se posent dès qu'il est fait abstraction de l'équipage.

La deuxième journée a débuté par un cours sur «Les outils d'optimisation et de validation des architectures et des logiciels des systèmes» qui a souligné le besoin d'optimisation, ainsi que les techniques déjà disponibles. Le cours sur «Les spécifications de conception et d'aptitude au vol des systèmes UAV», a ensuite examiné les conséquences pour la sécurité et les facteurs à prendre en considération lors de l'achat d'un UAV. Les spécifications de conception à suivre lors de l'établissement des spécifications techniques d'un véhicule aérien ont été décrites. Enfin, certains aspects du contrôle des véhicules et de leurs charges utiles ont été traités lors du cours sur «Les UAV et les liaisons de données : Tâches, types, techniques et exemples».

Le mercredi, un cours a été donné sur «Les défis liés au développement et à l'utilisation opérationnelle de la propulsion aérobie des UAV et UCAV». L'intérêt, les avantages et les désavantages de différents types de technologies de propulsion pour UAV ont été étudiés. Des études de cas concernant les Pioneer, Predator et Global Hawk ont été présentées. L'après-midi a été consacré aux micro-véhicules aériens. Une communication intitulée «Les micro-avions et les robots aériens : Missions et critères de conception» a fait un tour d'horizon des questions d'actualité concernant la conception et le choix de missions appropriées pour cette catégorie de véhicules aériens sans pilote.

«Les mesures aérodynamiques aux faibles nombres de Reynolds pour les micro-véhicules aériens à voilure fixe» a été le sujet d'un cours d'une demi-journée le jeudi. Les résultats d'une étude sur les méthodes d'obtention de données fiables sur les forces et les moments exercés sur les voitures minces en soufflerie et en tunnel hydrodynamique ont été présentés, ainsi que les caractéristiques de centrage et leur validation. La communication sur «Les charges utiles tactiques pour UAV» a décrit différents types de capteurs d'images et autres.

Le vendredi, les radars à synthèse d'ouverture SAR ont été le principal sujet de la communication sur «Les différents capteurs embarqués sur UAV». Les principes de fonctionnement, les défis et le développement de ce capteur complexe ont été exprimés d'une manière claire et compréhensible même pour l'observateur inexpérimenté. La communication sur «L'analyse des cas d'utilisation et la définition des caractéristiques fonctionnelles des systèmes complexes : Une étude de cas pour les UAV» a présenté un exemple de mise en œuvre d'outils mathématiques modernes pour l'élaboration d'un appel d'offre (RFP). Enfin, la dernière communication sur «Le système UAV B-Hunter», a illustré certaines modifications et améliorations apportées à l'UAV Hunter afin de répondre aux exigences du RFP émis par l'armée Belge.

Contents

	Page
Executive Summary	iii
Synthèse	iv
Publications of the RTO Applied Vehicle Technology Panel	vi
Special Course Staff	viii
Reference	
UAVs – Current Situation and Considerations for the Way Forward	1
by P. van Blyenburgh	
Airspace Policy and Air Traffic Management – UAV System Challenges	2A
by A.J. Clot	
Communications, Command, and Control – The Crowded Spectrum	2B
by A.J. Clot	
Tools for Optimization and Validation of System Architecture and Software	3
by C. Fargeon	
Design and Airworthiness Requirements for Military Unmanned Air Vehicle Systems	4
by B.C. Rogers	
UAV Data-Links: Tasks, Types, Technologies and Examples	5
by W.W. Rochus	
The Development and Operational Challenges of UAV and UCAV Airbreathing Propulsion	6
by A. Cifone and W. Parsons	
MicroFlyers and Aerial Robots – Missions and Design Criteria	7
by R.C. Michelson	
Aerodynamic Measurements at Low Reynolds Numbers for Fixed Wing Micro-Air Vehicles	8
by T.J. Mueller	
Tactical Payloads for UAVs	9
by A. Houle Carruso	
Various Sensors Aboard UAVs	10
by E.J. Schweicher	
The B-Hunter UAV System	11
by R. Delogne	
Résolution Systématique du Problème d’Etablissement des Spécifications Fonctionnelles pour les Systèmes d’Armes Complexes – Méthode des “Use Cases” – Application au Projet UAV	12*
by M. van Strythem	

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MP-37, Spring 2000

Structural Aspects of Flexible Aircraft Control
MP-36, Spring 2000

Aerodynamic Design and Optimization of Flight Vehicles in a Concurrent Multi-Disciplinary Environment
MP-35, Spring 2000

Gas Turbine Operation and Technology for Land, Sea and Air Propulsion and Power Systems (Unclassified)
MP-34, Spring 2000

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MP-25, Spring 2000

Small Rocket Motors and Gas Generators for Land, Sea and Air Launched Weapons Systems
MP-23, April 2000

Application of Damage Tolerance Principles for Improved Airworthiness of Rotorcraft
MP-24, January 2000

Gas Turbine Engine Combustion, Emissions and Alternative Fuels
MP-14, June 1999

Fatigue in the Presence of Corrosion
MP-18, March 1999

Qualification of Life Extension Schemes for Engine Components
MP-17, March 1999

Fluid Dynamics Problems of Vehicles Operation Near or in the Air-Sea Interface
MP-15, February 1999

Design Principles and Methods for Aircraft Gas Turbine Engines
MP-8, February 1999

Airframe Inspection Reliability under Field/Depot Conditions
MP-10, November 1998

Intelligent Processing of High Performance Materials
MP-9, November 1998

Exploitation of Structural Loads/Health Data for Reduced Cycle Costs
MP-7, November 1998

Missile Aerodynamics
MP-5, November 1998

EDUCATIONAL NOTES

Measurement Techniques for High Enthalpy and Plasma Flows
EN-8, Spring 2000

Development and Operation of UAVs for Military and Civil Applications
EN-9, April 2000

Planar Optical Measurements Methods for Gas Turbine Engine Life
EN-6, September 1999

High Order Methods for Computational Physics, Published jointly with Springer-Verlag, Germany
EN-5, March 1999

Fluid Dynamics Research on Supersonic Aircraft
EN-4, November 1998

Integrated Multidisciplinary Design of High Pressure Multistage Compressor Systems
EN-1, September 1998

TECHNICAL REPORT

Recommended Practices for Monitoring Gas Turbine Engine Life Consumption
TR-28, Spring 2000

Verification and Validation Data for Computational Unsteady Aerodynamics
TR-26, Spring 2000

A Feasibility Study of Collaborative Multi-facility Windtunnel Testing for CFD Validation
TR-27, December 1999

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14. Abstract	<p>Lecture Notes for the RTO Applied Vehicle Panel (AVT) Special Course on "Development and Operation of UAVs for Military and Civil Applications" have been assembled in this report. The following topics were covered: Overview of current UAV systems and potential for the future, Design and airworthiness requirements, Propulsion systems, Airbreathing propulsion for UVAVs, Microflyers, Experimental research at low Reynolds numbers, Payloads and sensors, Datalinks, Airspace policy, Air traffic management and Tools for software and system architecture validation.</p> <p>The material assembled in this report was prepared under the combined sponsorship of the RTO Applied Vehicle Technology Panel, the Consultant and Exchange Programme of RTO, the von Kármán Institute for Fluid Dynamics (VKI), and the NATO Partnership for Peace Programme.</p>		



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